Shannon Way, Tewkesbury, Gloucestershire. GL20 8ND United Kingdom

Tel: +44 (0)1684 292 333 Fax: +44 (0)1684 297 929 187 Northpointe Blvd, Suite 105 Freeport, PA 16229 United States of America

Tel: +1 724-472-4100 Fax: +1 724-472-4101 Tomson Centre 188 Zhang Yang Rd., B1602 Pudong New Area, Shanghai, Postal code: 200122 CHINA

Tel/Fax: +86 21 587 97659

SCMC House 16/6 Vishal Nagar Pimpale Nilakh, Wakad, Pune PIN 411027 INDIA

Tel: +91 827 506 5441





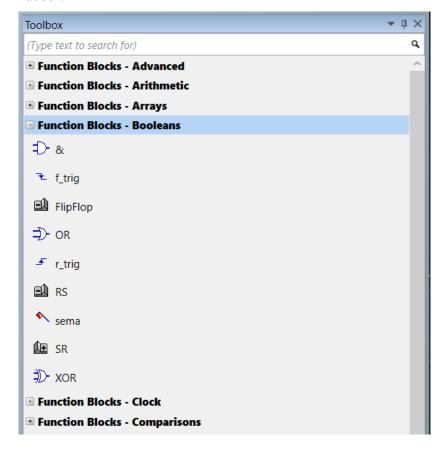
APPLICATION NOTE

1. Requirement

To add Rising Edge, Flip-Flop and Timer functions to a Ladder program.

2. Toolbox

Open the toolbox, select the required function blocks and drag them to the required position on the Ladder.

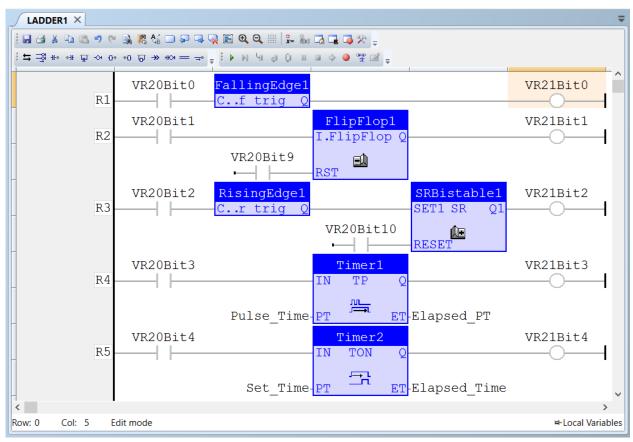


Name: GD Cat IEC PLC Page 1 of 7



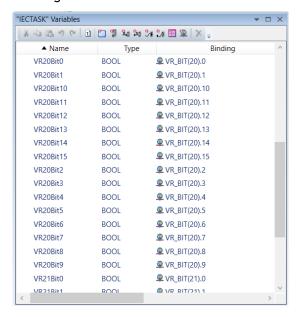
3. Assign instance names to the Function Blocks

As you put the functions into the Ladder, the editor will ask for names if they are needed. Names like RisingEdge1 were used in this example. More meaningful names can be used in the real application.



4. Bind contacts and coils as required

Usually the contacts will be inputs and the coils will be outputs. In this example they are bound to bits in global VR variables.

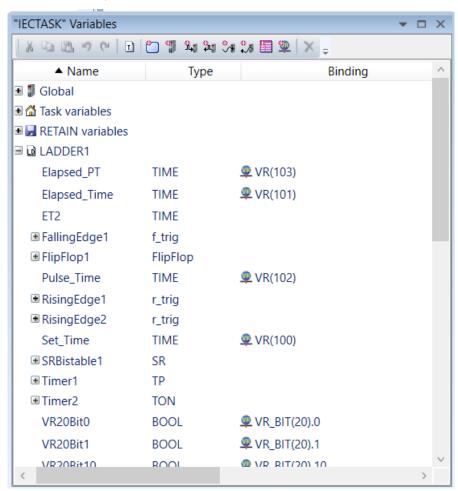


Name: GD Cat IEC PLC Page 2 of 7



5. Set up TIME variables for the timers

Timers need times as input and output as type TIME. In this case the variables are bound to VRs. The VR value is always in milliseconds.



6. Set the time values and run the program

In Motion Perfect terminal 0, the time values are set in VR(100) and VR(102).



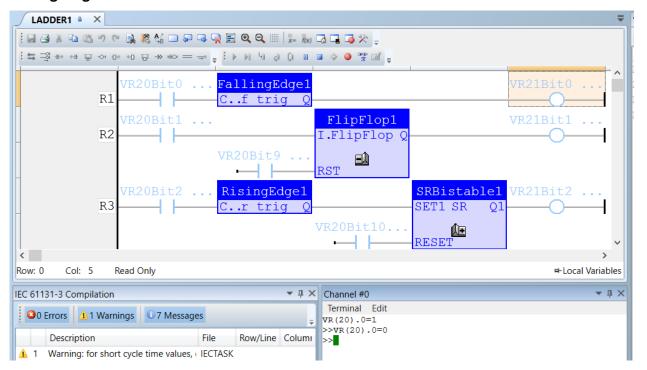
In this case 10 seconds and 5 seconds.

VR(20) bits are then set to trigger the different functions.

Name: GD Cat IEC PLC Page 3 of 7



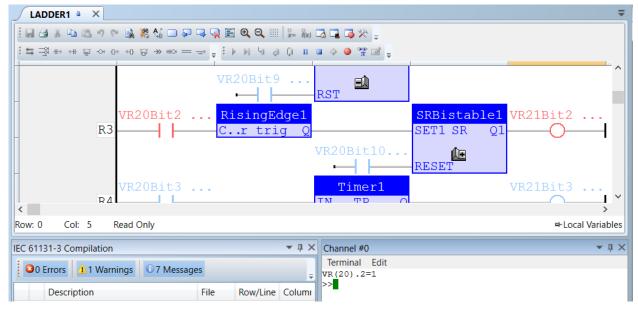
6.1. Falling Edge



There is a pulse on the Q output when VR(20) bit 0 goes to 0. It is difficult to see it.

6.2. Rising edge

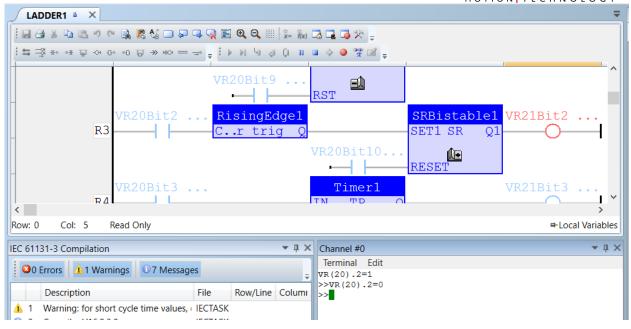
To make it easier to "see" the rising edge pulse, the output is connected to a SR bistable which will latch the value.



Setting the input High. The SR output is set because its input was pulsed from the Rising Edge Q output.

Name: GD Cat IEC PLC Page 4 of 7

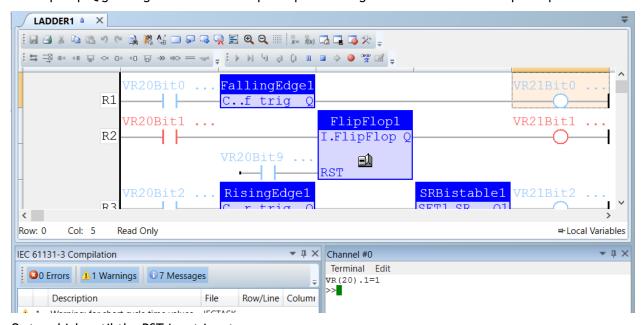




Setting the input low again.

6.3. Flip Flop

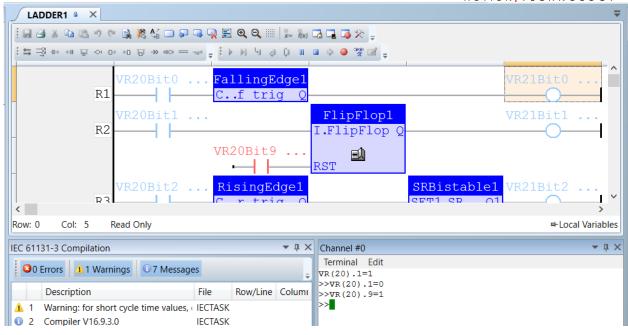
The flip flop Q goes high when the SET input is pulsed. It goes low when the RST input is pulsed.



Q stays high until the RST input is set.

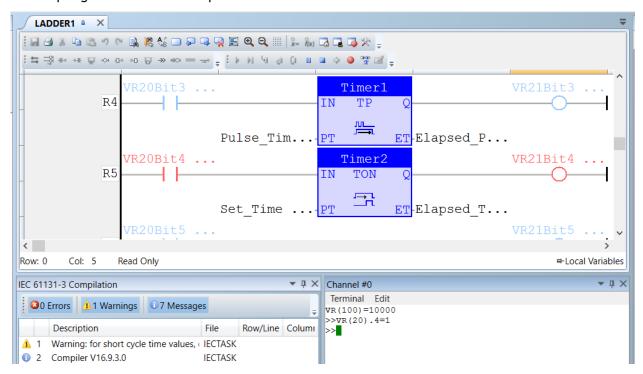
Name: GD Cat IEC PLC Page 5 of 7





6.4. TON timer

The output goes ON after the elapsed time is finished. In this case 10 seconds.

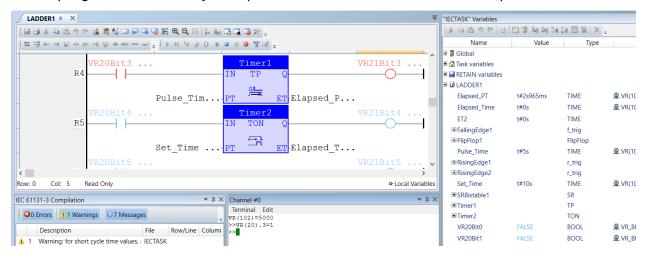


Name: GD Cat IEC PLC Page 6 of 7

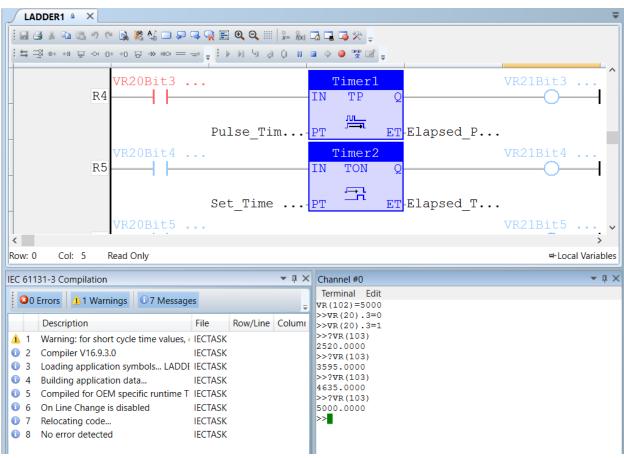


6.5. TP timer

The output goes ON immediately the input is set TRUE. It remains ON for the elapsed time.



You can also see the elapsed time in VR(103)



Name: GD Cat IEC PLC Page 7 of 7